

$$\Rightarrow P = \frac{Y - \psi}{X - 0} \Rightarrow \psi = Y - PX$$

$$\psi = Y(X) - P(X) \cdot X = Y(X(P)) - P(X(P)) \cdot X(P)$$


---

conversely. if we know  $\psi = \psi(P)$  ( $= Y - PX$ )

$$d\psi = dY - d(PX) = dY - \cancel{Pdx} - x dP$$

$$\downarrow \\ \frac{\partial Y}{\partial X}$$

$$= dY - \cancel{\frac{\partial Y}{\partial X} dx} - x dP = -x dP$$

$$\Rightarrow -x = \frac{d\psi}{dP} \rightarrow x = x(P) \rightarrow P = P(x)$$

eliminate "P"

$$Y = \psi - PX = \psi(P) - P \cdot x(P)$$

$$= \psi(P(x)) - P(x) \cdot x(P(x))$$


---

summary — single variable case.

$$Y = Y(x) \longleftrightarrow \psi = \psi(P)$$

$$P = \frac{dY}{dx} \longleftrightarrow -x = \frac{d\psi}{dP}$$

$$\psi = -Px + Y \longleftrightarrow Y = \psi - (-x) \cdot P \\ = xP + \psi$$

Eliminate X & Y

$$\psi = \psi(P) \longleftrightarrow Y = Y(x)$$

Eliminate P &  $\psi$

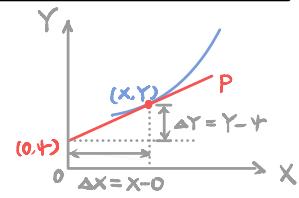
\*. For multivariable case.

$$Y = Y(x_0, x_1, \dots, x_t)$$

$$\Rightarrow P_k \equiv \frac{\partial Y}{\partial x_k}$$

$$(Y' = Y - P X)$$

$$Y' = Y - \sum_k P_k x_k$$



$$Y - Y' \approx dY$$

$$dY = \left( \frac{\partial Y}{\partial x_0} \right) dx_0 + \left( \frac{\partial Y}{\partial x_1} \right) dx_1 + \dots$$

$$= P_0 dx_0 + P_1 dx_1 + \dots$$

$$= \sum_k P_k dx_k = \sum_k P_k x_k = Y - Y'$$

$$x_k - 0 = x_k$$

$$\downarrow$$

$$\downarrow$$

$$dY = dY - \sum_k d(P_k x_k) = dY - \sum_k P_k dx_k - \sum_k x_k dP_k$$

$$= \sum_k P_k dx_k - \sum_k P_k dx_k - \sum_k x_k dP_k$$

$$= - \sum_k x_k dP_k$$

Now divide each side by  $dP_k$

$$\rightarrow \frac{dY}{dP_k} \equiv \frac{-x_k dP_k + \left( - \sum_{j \neq k}^t x_j dP_j \right)}{dP_k} \stackrel{\approx}{\rightarrow} - \sum_k x_k dP_k$$

$$= -x_k + \left( - \sum_{j \neq k} x_j \frac{\partial P_j}{\partial P_k} \right)$$

$$\downarrow$$

$$\Rightarrow -x_k$$

Equivalence.

$$Y = Y(x_0, x_1, \dots, x_t) \iff \psi = \psi(p_0, p_1, \dots, p_t)$$

▷ knowing  $Y = Y(x_0, x_1, \dots, x_t)$

$$\rightarrow \psi = Y - \sum_k p_k x_k = Y(\dots x_k \dots) + \sum_k p_k(x_k) \cdot x_k$$

⇒ since  $p_k \equiv \frac{\partial Y}{\partial x_k} \rightarrow p_k = p_k(x_k)$

$$\frac{\partial Y}{\partial x_k}$$

$$\Rightarrow x_k = x_k(p_k)$$

Eliminate  $x_k$

$$\Rightarrow \psi = Y(\dots x_k(p_k) \dots) + \sum_k p_k(x_k(p_k)) \cdot x_k(p_k)$$

likewise, if knowing  $\psi = \psi(\dots p_k \dots) \Leftrightarrow Y = Y(\dots x_k \dots)$

---

\* sub-space Legendre Transformation.

For multi-variable Legendre Transformation.

may be made w/  $(n+2)$  D of the Full space

$(t+2)$  D defined by  $Y = Y(x_0, x_1, \dots, x_t) \quad (n < t)$

$(t+2)$  D.

sub-space Legendre Transformed function

$$Y_\psi = \underbrace{Y_\psi(p_0, p_1, \dots, p_n)}_{1 \overline{(n+2)D}} \underbrace{x_{n+1} \dots x_t}_{n+1}$$

$$Y_F = Y_F(\{P_k\}, \{X_j\})$$

$$\tilde{\partial Y} \leftarrow \begin{matrix} 0 \leq k \leq n \\ n+1 \leq j \leq t \end{matrix} \rightarrow \tilde{\partial Y}$$

$$\Rightarrow P_k \equiv \frac{\partial Y_F}{\partial X_k}, \quad -X_k \equiv \frac{\partial Y_F}{\partial P_k}$$

$$P_k = \frac{\partial Y}{\partial X_k} \quad -X_k = \frac{\partial Y}{\partial P_k}$$

$\Rightarrow$  change of  $Y_F$  (i.e.  $dY_F$ ) is contributed from.

$$\{P_k\} \quad \& \quad \{\dots X_j \dots\}$$

$$k \leq n \quad n+1 < j \leq t$$

$$\Rightarrow dY_F = dY_F(\{P_k\}) + dY_F(\{X_j\})$$

$$= \sum \underbrace{\frac{\partial Y_F}{\partial P_k} \cdot dP_k}_{-X_k} + \sum \underbrace{\frac{\partial Y_F}{\partial X_j} dX_j}_{P_j}$$

$$= - \sum_{k=0}^n X_k dP_k + \sum_{j=n+1}^t P_j dX_j$$

$$\Rightarrow dY = \sum_0^t \left( \frac{\partial Y}{\partial X_i} \right) dX_i = \sum_0^t P_i dX_i$$

$$= \sum_0^n P_k dX_k + \sum_{n+1}^t P_j dX_j$$

$$\cancel{\Rightarrow dY - dY_F = \sum_0^n P_k dX_k + \sum_{n+1}^t P_j dX_j - \left( - \sum_{k=0}^n X_k dP_k + \sum_{j=n+1}^t P_j dX_j \right)}$$

$$= \sum_0^n P_k dX_k + \sum_{k=0}^n X_k dP_k$$

$$= \sum_0^n d(P_k X_k)$$

## 5> Integration

$$\int dY - \int dY_F = \int \sum_0^n d(P_k X_k)$$
$$\Rightarrow Y = Y_F + \sum_0^n P_k X_k$$

---

## Lagrangian Mechanics.

Hamiltonian

2r # of variables

$$Y \leftarrow L = L(v_1, v_2, \dots, v_r; q_1, q_2, \dots, q_r)$$
$$\{v\} \qquad \{q\}$$

momenta  $\equiv P_k \equiv \frac{\partial L}{\partial v_k}$   
(Generalized)

$$Y_F \leftarrow H = H(P_1, P_2, \dots, P_r; q_1, q_2, \dots, q_r)$$
$$\{P\} \qquad \{q\}$$

$$-H = L - \sum_1^r P_k v_k$$

$$\hat{H} = \hat{T} + \hat{V}$$

---

## 3. Thermodynamic Potentials.

$$Y = Y(X_0, X_1, \dots, X_t)$$

$$U = U(S, V, N_1, N_2, \dots)$$

$$P_0, P_1, \dots$$

$$T, -P, \mu$$

sub-space Legendre Transformation

$$Y_F = Y_F(P_0, X_1, \dots, X_t)$$

$$U_F = U_F(T, V, N_1, \dots)$$

---

\* Helmholtz potential

$$F \equiv U[T]$$